Motivation	Syntax	Semantics	Conclusion
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A First-Order Logic with First-Class Types

Michael Walter joint work with Peter H. Schmitt and Mattias Ulbrich

Institute for Theoretical Computer Science University of Karlsruhe

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Motivation	Syntax	Semantics	Conclusion
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JAVA CARD DL			

- modal logic behind KgY
- based on a typed first-order logic with subtyping, type predicates and casts [Gie05]

$$\forall x : \text{Object} : x \models \text{Array} \rightarrow \text{length}((\text{Array})x) \ge 0$$

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• we focus only on this first-order part

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JAVA Generics			

• classes parametrized by type parameters

```
public class Array<T>
{
    public T last();
}
```

• Array $\langle T \rangle \sqsubseteq$ Array $\langle ? \rangle \sqsubseteq$ Object

• what is the signature of last?

 $\{ \mathsf{last}_{\mathcal{T}} : \mathsf{Array}\langle \mathcal{T} \rangle \to \mathcal{T} \}$

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{ last $_T$: Array $\langle T \rangle \rightarrow T$ }

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First-Class Types			

{ last $_{\mathcal{T}}$: Array $\langle \mathcal{T} \rangle \rightarrow \mathcal{T}$ }

how to reason about arrays without fixing the element type?



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First-Class Types			

$$\{ \mathsf{last}_{\mathcal{T}} : \mathsf{Array}\langle \mathcal{T} \rangle \to \mathcal{T} \}$$

how to reason about arrays without fixing the element type?

single signature

 $\begin{array}{l} \mathsf{last}:\mathsf{Array}\langle ?\rangle \to \top \\ \mathsf{T}:\mathsf{Array}\langle ?\rangle \to \mathbb{T} \end{array}$

with type of all types \mathbb{T}

• need to assert that the return value has proper type

 $\forall a : \operatorname{Array} \langle ? \rangle$. $\operatorname{last}(a) \equiv T(a)$

with binary predicate \equiv

```
(\rightsquigarrow universal types)
```

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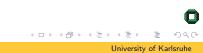
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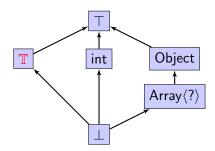


Syntax 000

Type Hierarchy

Definition (Type hierarchy)

- set of types T
- subtype relation \sqsubseteq
- universal type \top and empty type ⊥
- greatest lower bounds (□)
- type of all types \mathbb{T}



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Semantics 000000

Signature

Definition (Signature)

- predicate, function and variable symbols with types
- predefined symbols:
 - equality $\doteq: \top \times \top$ • type predicate $\equiv: \top \times \mathbb{T}$
 - subtype predicate $\Box : \mathbb{T} \times \mathbb{T}$
 - type intersection $\Box : \mathbb{T} \times \mathbb{T} \to \mathbb{T}$
 - type constants $T : \rightarrow \mathbb{T}$
 - casts

(for each type $\mathcal{T} \in \mathcal{T}$)



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Torms and E	armulaa		

Definition (Term of	type <i>T</i>)
• V	if $v : T$ variable symbol
• $f(t_1,\ldots,t_n)$	if $f: T_1 \times \ldots \times T_n \to T$ function symbol, t_i term of type $T'_i \sqsubseteq T_i$

Definition (Formula)

•
$$p(t_1,...,t_n)$$
 if ...

•
$$\neg \varphi$$
, $\varphi \lor \psi$, $\varphi \land \psi$, $\varphi \to \psi$

•
$$\forall v.\varphi, \exists v.\varphi$$

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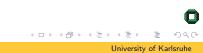
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Motivation	Syntax	Semantics	Conclusion
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Structure			

Definition (Structure)

- \bullet domain ${\cal D}$
- dynamic typing function $\delta : \mathcal{D} \to \mathcal{T}$

$$\rightsquigarrow \mathcal{D}_{\mathcal{T}} := \{x \in \mathcal{D} : \delta(x) \sqsubseteq \mathcal{T}\}$$

 \bullet interpretation ${\cal I}$ of functions and predicates

$$\mathcal{I}(f): \mathcal{D}_{\mathcal{T}_1} \times \ldots \times \mathcal{D}_{\mathcal{T}_n} \to \mathcal{D}_{\mathcal{T}}$$
$$\mathcal{I}(p) \sqsubseteq \mathcal{D}_{\mathcal{T}_1} \times \ldots \times \mathcal{D}_{\mathcal{T}_n}$$

 \rightsquigarrow value of a term, validity of a formula. . .



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how about the predefined symbols?

 \rightsquigarrow value of a term, validity of a formula. . .



Motivation	Syntax	Semantics	Conclusion
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Interpretation			

 $\bullet \ \mathcal{D}_{\mathbb{T}} = \mathcal{T}$

• predefined symbols shall agree with their type hierarchy counterpart:

$$\mathcal{I}(\sqsubseteq) \ni (x, T) \iff x \in \mathcal{D}_T \iff \delta(x) \sqsubseteq T$$
$$\mathcal{I}(\sqsubseteq) = \sqsubseteq, \ \mathcal{I}(T) = T, \dots$$

Observation

If the type hierarchy is infinite then the logic has no sound and complete calculus. ${\not \! _2}$

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Constant			
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Motivation	Syntax	Semantics	Conclusion

Completeness and Compactness

Definition ((Strong) completeness)

$$\mathcal{A} \models \varphi \quad \Rightarrow \quad \mathcal{A} \vdash \varphi$$

Compactness Theorem

Every logic which has a sound and complete calculus is compact: If some set of formulae is not satisfiable then there exists a finite subset which is already not satisfiable.



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Reasons for	Noncompactness		

two obstructions to compactness

 ${\color{black} 0}$ constant symbols generate domain of ${\mathbb T}$

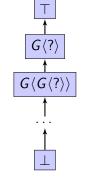
$$\{\neg(c \doteq T) : T \in T\} \notin$$

(for infinite \mathcal{T} ; compare \mathbb{N})









Inon-Noetherian type hierarchies

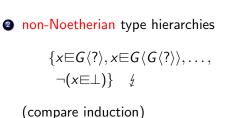
$$\{ x \equiv G \langle ? \rangle, x \equiv G \langle G \langle ? \rangle \rangle, \dots, \\ \neg (x \equiv \bot) \} \notin$$

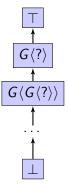
(compare induction)

Theorem (Giese)

The logic of [Gie05] has a sound and complete calculus if and only if the type hierarchy is Noetherian.







Theorem (Giese)

The logic of [Gie05] has a sound and complete calculus if and only if the type hierarchy is Noetherian.

Motivation	Syntax	Semantics	Conclusion
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Interpretation	- Modified		

- \bullet require $\mathcal{D}_{\mathbb{T}}$ to be a type hierarchy that contains $(\mathcal{T},\sqsubseteq)$
- predefined symbols shall extend their type hierarchy counterparts
- sanity conditions

Theorem

The modified logic has a sound and complete calculus if and only if the type hierarchy is Noetherian.

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Conclusion

- characterized completeness of the logic of [Gie05]
- characterized completeness of first-class types
- first-class types are not useful on their own $\frac{1}{2}$ \sim universal types, dependent types

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Martin Giese.

A Calculus for Type Predicates and Type Coercion. In Bernhard Becker, editor, *Proceedings of the 14th International Conference on Automated Reasoning with Analytic Tableaux and Related Methods (TABLEAUX 2005)*, Lecture Notes in Artificial Intelligence, pages 123–137. Springer, 2005.

